

Package: tidysdm (via r-universe)

November 20, 2024

Title Species Distribution Modelling with Tidymodels

Version 0.0.0.9000

Description Provides functions and classes to help create Species Distribution Models (SDMs) within the {tidymodels} framework. Provides new {parsnip} models, new {recipes} steps, and {yardstick} metrics. This package provides access to the powerful {tidymodels} ecosystem for SDMs, especially the package {spatialsample} for spatially aware cross validation and model evaluation, as well as opening up all classification models implemented in {parsnip} for presence-only SDMs, using the pseudo-absence approach.

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Encoding UTF-8

Roxygen list(markdown = TRUE)

RoxygenNote 7.2.3

Depends parsnip, R (>= 2.10), recipes

Imports dplyr, fasterize, ngeo, purrr, rlang (>= 0.4.11), sf, stars

Suggests knitr, rmarkdown, roxygen2, ENMTools, tidyverse, tidymodels, spatialsample, lwgeom, ranger, vip

VignetteBuilder knitr

URL <https://rdinnager.github.io/tidysdm/>

LazyData true

Remotes danlwarren/ENMTools

Config/pak/sysreqs libgdal-dev gdal-bin libgeos-dev libicu-dev
libssl-dev libproj-dev libsqlite3-dev libudunits2-dev

Repository <https://rdinnager.r-universe.dev>

RemoteUrl <https://github.com/rdinnager/tidysdm>

RemoteRef HEAD

RemoteSha 5b82b81199bdd661ef21d594b43157081c8ee5df

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<code>add_env_vars</code>	<i>Add environmental variables</i>
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Description

Add environmental variables

Usage

```
add_env_vars(x, env)
```

Arguments

`env`

<code>create_background</code>	<i>Make background from points</i>
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Description

Make background from points

Usage

```
create_background(
  x,
  method = c("convex_hull", "point_buffer", "ecoregion", "concave_hull", "grid_fill",
            "user_fill"),
  buffer = 0,
  max_bg = NULL,
  grid_options = NULL,
  concave_options = NULL
)
```

Arguments

concave_options

create_prediction_grid*Generate a grid of values for making predictions*

Description

Generate a grid of values for making predictions

Usage

create_prediction_grid(bg, n = 10000, square = TRUE, include_polygons = FALSE)

Arguments

include_polygons

get_spatial_neighbours*Get Spatial Neighbours*

Description

Get Spatial Neighbours

Usageget_spatial_neighbours(
 x,
 k = 8,
 maxdist = 1e+05,
 progress = TRUE,
 parallel = 1
)**Arguments**

x	An sf object
k	The number of nearest neighbours to retrieve
maxdist	The maximum distance to get nearest neighbours from
progress	Print progress bar?
parallel	How many parallel cores to use.

Value

A list of neighbour indices

`po_spatial_buffer_vfold_cv`

Spatial Cross Validation Designed for Presence-Only Data

Description

Spatial Cross Validation Designed for Presence-Only Data

Usage

```
po_spatial_buffer_vfold_cv(
  data,
  radius = NULL,
  buffer = 0.1,
  v = 10,
  repeats = 1,
  presence = NULL,
  pool = 0.1,
  ...
)
```

Arguments

...

`sdm_data`

Convert presence points and a background area into an `sdm_data` object suitable for a `tidy` workflow.

Description

Convert presence points and a background area into an `sdm_data` object suitable for a `tidy` workflow.

Usage

```
sdm_data(pres, bg, n = 500, abs = NULL, sample_options = list(), ...)
```

Arguments

pres	Points representing species occurrences. Should be an sf object with crs information
bg	A background area as an sf polygon or a raster mask (in stars or raster format)
n	Integer specifying the number of background or pseudo-absence points to sample from the background as specified by bg.
abs	Optionally an sf object with true absence data in the form of points.
...	

Value

A sdm_data object inheriting from a tibble

step_sample_pseudo_absences
Title

Description

Title

Usage

```
step_sample_pseudo_absences(  
  recipe,  
  bg_geometry = NULL,  
  role = NA,  
  trained = FALSE,  
  size,  
  options = list(type = "random", exact = FALSE),  
  skip = FALSE,  
  id = rand_id("sample_pseudo_absences")  
)
```

Arguments

id

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